

Annealing-Pareto Multi-Objective Multi-Armed Bandit Algorithm

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(MOMABs)

Pareto
Thomp-
son
Sampling

The
Annealing
Pareto
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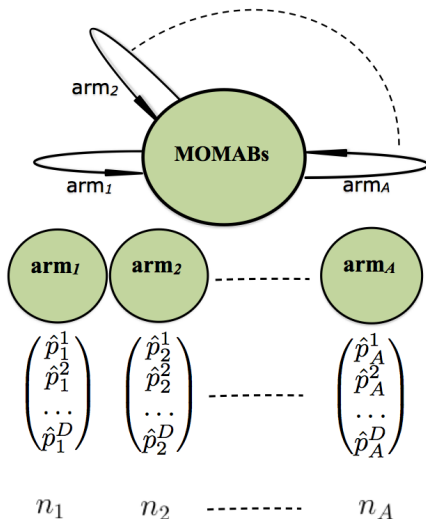
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Multi-Objective, Multi-Armed Bandits (MOMABs) Problem

The trade-off between exploration and exploitation



MOMABs Problem

The reward r_i^d , $r_i^d \in \{0, 1\}$ of an arm i in the objective d is drawn from a corresponding **Bernoulli probability distribution**.

$$\hat{p}_i^d(t) = \frac{\alpha_i^d(t)}{\alpha_i^d(t) + \beta_i^d(t)}$$

$$\text{where } \alpha_i^d(t) = \alpha_i^d(t-1) + 1, \quad \text{if } r_i^d = 1$$
$$\beta_i^d(t) = \beta_i^d(t-1) + 1, \quad \text{if } r_i^d = 0$$

$\alpha_i^d(t)$ is the number of successes, $\beta_i^d(t)$ is the number of failures and $\hat{p}_i^d(t)$ is the estimated probability of success of the arm i in the objective d at time step t .

MOMABs Problem

The Pareto Dominance Relations

- Arm i dominates or is better than j , $i \succ j$. If $\exists_d, i^d \succ j^d$ and $\forall_o, j \neq o, i^o \succeq j^o$.
- Arm i is incomparable with j , $i \parallel j$. If $i^d \succ j^d$ and $i^o \prec j^o$.
- Arm i is **not dominated** by j , $j \not\succeq i$. Either $i \parallel j$ or $i \succ j$.

Using the above relationships, the Pareto front A^* set is:

- The subset of A , i.e. $A^* \subset A$.
- The set of arms that are **not dominated** by all other arms.
- The Pareto optimal arms A^* are **incomparable** with each other.

MOMABs Algorithms

Pareto-UCB1

- Play initially each arm i initial steps.
- Estimate the probability of success vector $\hat{\mathbf{p}}_i$, $\hat{\mathbf{p}}_i = [\hat{p}_i^1, \dots, \hat{p}_i^D]^T$ for each arm i and add to each objective d an exploration bound ExpB_i^d .

$$\text{ExpB}_i^d(\text{UCB1}) = \sqrt{(2 \ln(t^4 \sqrt{D|A^*|})) / N_i}$$

D is the number of objectives, $|A^*|$ is the number of optimal arms, t is the current time step, and N_i is the number of times arm i has been selected.

- Find the Pareto set A' set such that $\forall_j \in A', \forall_k \notin A'$

$$\hat{\mathbf{p}}_k + \text{ExpB}_k \not\leq \hat{\mathbf{p}}_j + \text{ExpB}_j$$

- Choose uniformly at random an optimal arm i^* , $i^* \in A'$.
- Update the estimated probability of success vector $\hat{\mathbf{p}}_{i^*}$, and the number of times arm i^* is chosen N_{i^*} .

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The exploration bound ExpB_i^d for each arm i and objective d .

$$\text{ExpB}_i^d(\text{KG}) = |A|D * (L - t) * v_i^d, \text{ where}$$

$$v_i^d \triangleq \begin{cases} \frac{\alpha_i^d}{\alpha_i^d + \beta_i^d} \left(\frac{\alpha_i^d + 1}{\alpha_i^d + \beta_i^d + 1} - C_i^d \right), & \text{if } \frac{\alpha_i^d}{\alpha_i^d + \beta_i^d} \leq C_i^d < \frac{\alpha_i^d + 1}{\alpha_i^d + \beta_i^d + 1} \\ \frac{\beta_i^d}{\alpha_i^d + \beta_i^d} \left(C_i^d - \frac{\alpha_i^d}{\alpha_i^d + \beta_i^d + 1} \right), & \text{if } \frac{\alpha_i^d}{\alpha_i^d + \beta_i^d + 1} \leq C_i^d < \frac{\alpha_i^d}{\alpha_i^d + \beta_i^d} \\ 0 & \text{otherwise} \end{cases}$$

where

$$C_i^d = \max_{i \neq j} \alpha_j^d / (\alpha_j^d + \beta_j^d)$$

α_i^d , β_i^d , and v_i^d are the number of successes, number of failures, and the index of an arm i for dimension d , respectively. The total number of arms is $|A|$, L is the horizon of an experiment.

MOMABs Problem

MOMABs Algorithms (Pareto-UCB1 and Pareto-KG)

- Trade-off between exploration and exploitation by adding an exploration bound.
- The added exploration bound ExpB_i^d for the arm i in the objective d by Pareto-KG depends on all available arms in the objective d , each objective has different exploration bound.
- While, the added exploration bound ExpB_i^d for the arm i in the objective d by Pareto-UCB1 depends only on the arm i , each objective has the same exploration bound.

Pareto Thompson Sampling (PTS)

- Initially, the number of successes $\alpha_i^d = 1$ equals to the number of failures $\beta_i^d = 1$ for each arm i and objective d .
- For each arm i , in each objective d , the probability of selection P_i^d is sampled by using Beta distribution, $P_i^d = \text{Beta}(\alpha_i^d, \beta_i^d)$.
- Pareto set A' is found, such that $\forall j \in A', \forall k \notin A'$

$$P_k \not\prec P_j$$

- Choose uniformly at random an optimal arm i^* , $i^* \in A'$.
- Observes $\mathbf{r}_{i^*} = [r_{i^*}^1, \dots, r_{i^*}^D]^T$ and updates the number of successes $\alpha_{i^*}^d$ and the number of failures $\beta_{i^*}^d$ for each d .

The Annealing Pareto Algorithm

Annealing-Pareto has a **specific mechanism to control the trade-off between exploration and exploitation**. It uses an exponential decay ϵ_t , $\epsilon_t = \epsilon_{decay}^t / (|A||D|)$ with Pareto dominance relation, where ϵ_{decay} is the decay factor parameter.

- Play initially each arm i initial steps, initialize the ϵ -Pareto front set $A_\epsilon^*(0) = A$.
- at each t
 - Set the decay parameter $\epsilon_t = \epsilon_{decay}^t / (|A||D|)$
 - For each objective $d \in D$: $i \in S(t)^d$ if $\hat{\mu}_i^d \in [\hat{\mu}^{*,d} - \epsilon_t, \hat{\mu}^{*,d}]$,
 - $S(t) \leftarrow S^1(t) \cup S^2(t) \cup \dots \cup S^D(t)$
 - $S_{diff} \leftarrow A_\epsilon^*(t-1) - S(t)$
 - For arm $j \in S_{diff}$; If $\hat{\mu}_k \not\prec \hat{\mu}_j, \forall k \in A$, then $S(t) \leftarrow S(t) \cup j$
 - $A_\epsilon^*(t) \leftarrow S(t)$
 - Select an optimal arm i^* uniformly, at random from $A_\epsilon^*(t)$;
Update: $\hat{\mu}_{i^*}, N_{i^*}$; Compute: the unfairness and Pareto regrets.

The Annealing Pareto Algorithm

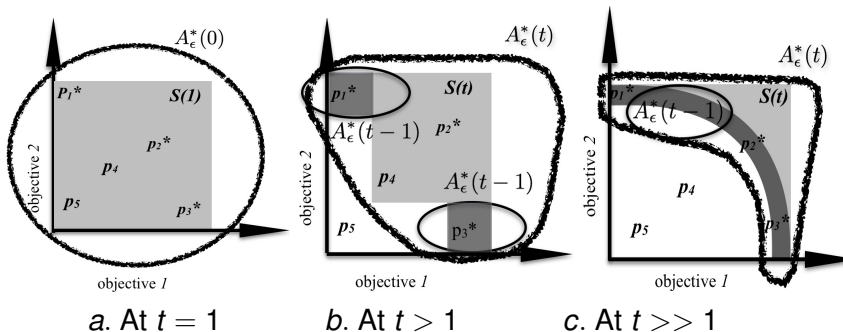


Figure : The dynamic of the annealing-Pareto algorithm.

Performance in MOMABs

- 1 Pareto regret** measures the distance between a probability of success vector of an arm i that is pulled at time step t and the Pareto front A^* .
- 2 Unfairness regret** $R_{SE}(t)$ is the Shannon entropy which is a measure of disorder on the Pareto front A^* . The higher the entropy, the higher the disorder.

Experimental Comparison

Experimental Setup

We experimentally compare Pareto-UCB1, Pareto-KG, Pareto Thompson sampling, and annealing-Pareto algorithms.

The performance measures are:

- 1** The average Pareto and the cumulative average Pareto regret at each time step which are averaged of M experiments.
- 2** The average unfairness and the cumulative average unfairness regret at each time step which are averaged of M experiments.

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Experimental Comparison

Experiment 1: 2-objectives, 6-arms

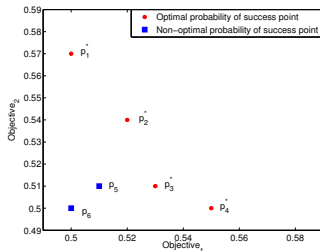
The true probability
of success vector set is

$$\{p_1 = \begin{bmatrix} .55 \\ .5 \end{bmatrix}, p_2 = \begin{bmatrix} .53 \\ .51 \end{bmatrix},$$

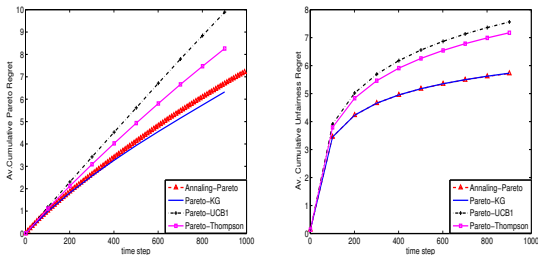
$$p_3 = \begin{bmatrix} .52 \\ .54 \end{bmatrix}, p_4 = \begin{bmatrix} .5 \\ .57 \end{bmatrix},$$

$$p_5 = \begin{bmatrix} .51 \\ .51 \end{bmatrix}, p_6 = \begin{bmatrix} .5 \\ .5 \end{bmatrix} \}$$

Note that the Pareto front
set is $A^* = \{a_1^*, a_2^*, a_3^*, a_4^*\}$



Experimental Comparison

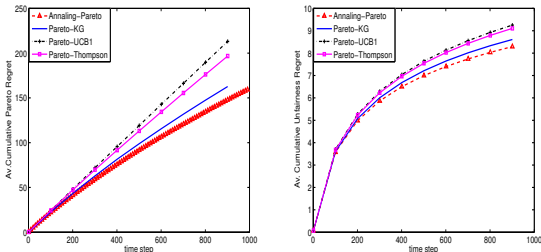


a. Pareto cumulative regret b. Unfairness cumulative regret

Figure : Performance comparison on 2-objective, 6-armed with non-convex probability of success vector set. Sub-figure *a* shows the average Pareto cumulative regret. Sub-figure *b* shows the average cumulative unfairness regret.

Experimental Comparison

Experiment 2: 5-objectives, 20-arms We add extra 3 objectives and 14 arms to Experiment 1, resulting in 5-objective, 20-armed. Pareto front contains 7 optimal arms.



a. Pareto cumulative regret b. Unfairness cumulative regret

Figure : Performance comparison on 5-objective, 20-armed with non-convex probability of success vector set. The average cumulative Pareto and unfairness regret performances are shown in sub-figures a and b, respectively.

Overview of the state of the Art

- 1** We extended Pareto Thompson sampling to the MOMAB.
- 2** We proposed annealing-Pareto algorithm.
- 3** We proposed using the entropy measure as a performance measure in the MOMAB.
- 4** We studied empirically the trade-off between exploration and exploitation in the MOMAB, where we compared Pareto-KG, Pareto-UCB1, Pareto Thompson sampling and the annealing-Pareto.

Thanks For Your Attention!

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